



Comportement en temps long d'équations cinétiques avec effets de bord

Thèse encadrée par Nicolas Fournier (SU-LPSM) et Stéphane
Mischler (PSL-CEREMADE)

Armand Bernou

LPSM, Sorbonne Université

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Long-Time Behavior of Kinetic Equations with Boundary Effects

Kinetic Theory

Introduction

Free molecular flow

Boundary conditions

Probabilistic approach for the asymptotic behavior of the FTE

Analytic method, Harris' theorems

Linearized equations from collisional kinetic theory

Outlook



Kinetic theory I

Consider a volume full of a gas made of molecules. Microscopically, the dynamics of each gas particle is well-described by Newton's laws. If we only had two molecules and an ideal wall, the problem would be quite easy to study.



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One possible model: a system of hard-spheres with no outside force and a simple boundary condition.



Kinetic theory II



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2. Studying microscopically the system makes it difficult to understand the behavior of macroscopic quantities, e.g. the temperature.

In kinetic theory, we adopt a statistical view of the system. The idea is to analyze the behavior of a “typical” particle, rather than trying to follow all of them. This is also the good point of view for the study of the convergence towards some equilibrium.



A basic example: free molecular flow

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The corresponding PDE for the probability density function $f(t, x, v)$ of finding a particle in position $x \in \Omega$, at time $t \geq 0$, with velocity $v \in \mathbb{R}^d$ is

$$\partial_t f(t, x, v) + v \cdot \nabla_x f(t, x, v) = 0, \quad (t, x, v) \in \mathbb{R}_+ \times \Omega \times \mathbb{R}^d.$$



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This is the (kinetic) free-transport equation inside the bounded domain $\Omega \subset \mathbb{R}^d$. It must be completed with

- an initial condition $f_0(\cdot, \cdot)$ on $\Omega \times \mathbb{R}^d$;
- some conditions at the boundary $\partial\Omega$ of the spatial domain.



A view of the free-molecular flow



Boundary conditions

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Specular reflection

Let $x \in \partial\Omega$ the boundary of Ω , n_x the unit outward normal vector at x , $v \in \mathbb{R}^d$ such that $v \cdot n_x > 0$, then

$$\eta_x(v) = v - 2(v \cdot n_x)n_x,$$

is the outgoing velocity of the particle (i.e. after the reflection).



Boundary conditions

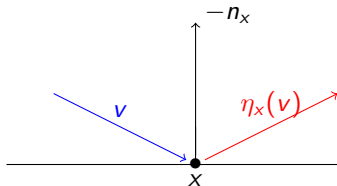
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For instance, with such condition, the gas exerts no stress on the boundary in the tangential directions. In practice, a surface tension is observed.

To understand why this model is not accurate, one needs to remember that the wall is itself made of molecules ! And possibly, of several layers of spaced ones...



Diffuse reflection

One answer, given by Maxwell himself, is to replace (at least a part of) the specular reflection by the **diffuse reflection**.



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Diffuse reflection

Let $\Sigma := \partial\Omega \times \mathbb{R}^d$. At the boundary, the density f satisfies, for $(t, x, v) \in \mathbb{R}_+ \times \Sigma$, with $v \cdot n_x < 0$,

$$f(t, x, v) = cM(v)\widetilde{\gamma_+ f}(t, x),$$

where c is a normalizing constant and $\widetilde{\gamma_+ f}$ is the flux, given by

$$\widetilde{\gamma_+ f}(t, x) = \int_{\{v' \cdot n_x > 0\}} f(t, x, v') |v' \cdot n_x| dv'.$$



The kernel M

The most interesting case is the wall Maxwellian:

$$M(v) = \frac{e^{-\frac{|v|^2}{2}}}{(2\pi)^{\frac{d}{2}}}.$$

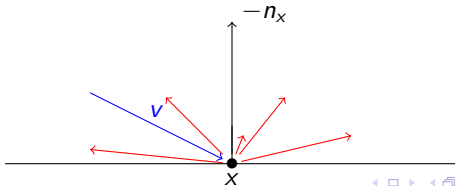
Extensions/other choices are possible:

1. a dependency of the temperature in x . Then

$$c(x)M(x, v) = c(x)e^{-\frac{|v|^2}{2\theta(x)}} \text{ with } \theta(x) \text{ the temperature at } x \in \partial\Omega, \\ c(x) \text{ a normalizing constant.}$$

2. Stochastic billiards: M conserves energy, but no radial symmetry.

Hereafter we assume radial symmetry and continuity around 0.





The Maxwell boundary condition

Combining both conditions gives a more accurate description.

Maxwell boundary condition

For $(t, x, v) \in \mathbb{R}_+ \times \Sigma$ with $v \cdot n_x < 0$,

$$f(t, x, v) = (1 - \alpha(x))f(t, x, \eta_x(v)) + \alpha(x)cM(v)\widetilde{\gamma}_+ f(t, x),$$

with $\alpha(x)$ the **accommodation** coefficient at $x \in \partial\Omega$.



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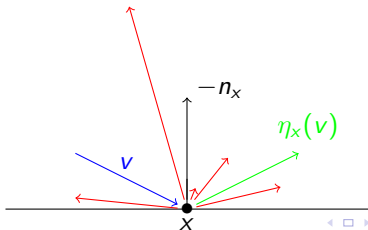
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Application of the coupling method [Chapter 2]

Numerical study through the simulation of a particle system [Chapter 3]

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Model and hypotheses

We consider the free-transport equation with Maxwell boundary condition, constant temperature, $d \geq 2$. We assume that Ω has volume 1 in what follows. We set $G := \Omega \times \mathbb{R}^d$ and let $f_0 \in L^1(G)$.

It is known (Arkeryd-Cercignani) that the equation admits a unique solution f such that $f(t, \cdot, \cdot) \in L^1(G)$ for all $t \geq 0$. Alternatively we may work with measures, but there is then no uniqueness. We want to understand the behavior, when $t \rightarrow \infty$, of this solution.



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A first key hypothesis: for all $x \in \partial\Omega$, $\alpha(x) \geq \alpha_0$ for some $\alpha_0 > 0$. If $\alpha \equiv 0$, no equilibrium.

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The purely specular case



Qualitative convergence towards equilibrium

The system has a natural entropy: setting $W(t) = \int_G f \ln\left(\frac{f}{M}\right) dv dx \geq 0$,

$$\frac{d}{dt} W(t) \leq 0.$$

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Also, if $f(t, x, v) = M(v)$ for all $(t, x, v) \in \mathbb{R}_+ \times G$, $W(t) = 0$ for all $t \geq 0$.

One can in fact show (Arkeryd-Nouri) that, starting with f_0 having mass 1, regular enough, f converges towards

$$f_\infty(x, v) = M(v).$$

Key question: what is the rate at which this convergence occurs in the L^1 norm? Slow velocities persist a long time \rightarrow no exponential convergence.



Known results for this problem (wall Maxwellian)

Results in L^1 norm, in a radially symmetric domain $\Omega = \mathbb{S}^{d-1}$:



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A convergence in a non-symmetric domain



First strategy: the coupling method [Chapter 2]

Key idea 1: it is possible to build a process $(X_t, V_t)_{t \geq 0}$ whose law is a solution to the free-transport equation with Maxwell boundary condition. Some randomness appears in this construction.



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Key idea 2 (technically harder): we can find a coupling (i.e. two constructions with correlated randomnesses) $(X_t, V_t, \tilde{X}_t, \tilde{V}_t)_{t \geq 0}$ s.t. $(X_0, V_0) \sim f_0$, $(\tilde{X}_0, \tilde{V}_0) \sim f_\infty$ and, for

$$\tau = \inf\{t > 0, (X_{t+s}, V_{t+s})_{s \geq 0} = (\tilde{X}_{t+s}, \tilde{V}_{t+s})_{s \geq 0}\},$$

we can show (when M is the Maxwellian wall) the inequality $\mathbb{E}[\tau^{d-}] < \infty$.



Conclusion from the coupling

Once the control on τ is established, we conclude using properties of the total variation distance: if $(X_t, V_t) \sim f_t$ the solution at time t and $(\tilde{X}_t, \tilde{V}_t) \sim f_\infty$, then

$$\begin{aligned} \|f_t - f_\infty\|_{TV} &= \inf_{(X, V) \sim f_t, (\tilde{X}, \tilde{V}) \sim f_\infty} \mathbb{P}((X, V) \neq (\tilde{X}, \tilde{V})) \\ &\leq \mathbb{P}(\tau > t) \leq \frac{\mathbb{E}[(\tau + 1)^{d-1}]}{(t + 1)^{d-1}}, \end{aligned}$$

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This strategy also allows one to work in the framework of measures, although the solution f_t is not unique in this case.



Results

Theorem (B., Fournier)

Let Ω be a C^2 bounded domain, $G := \Omega \times \mathbb{R}^d$. Let $f_0 \in L^1(G)$ and write f_t for the unique solution at time $t \geq 0$. If $r : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is increasing with $r(x+y) \lesssim r(x) + r(y)$, and

$$\int_G r\left(\frac{1}{|v|}\right) f_0(x, v) \, dv dx + \int_G r\left(\frac{1}{|v|}\right) M(v) \, dv dx < \infty,$$

then, for all $t \geq 0$, for some constant $C > 0$,

$$\|f_t - f_\infty\|_{L^1} \leq \frac{C}{r(t)}.$$



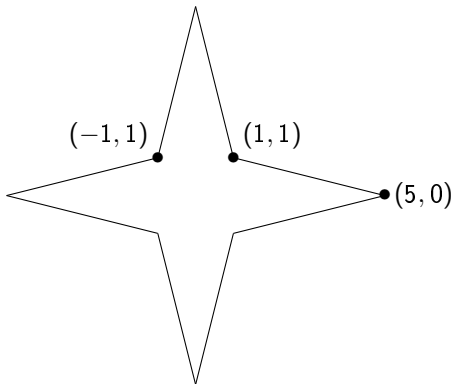
Numerical study of the asymptotic behavior [Chapter 3]

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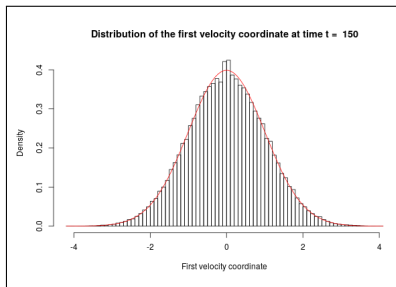
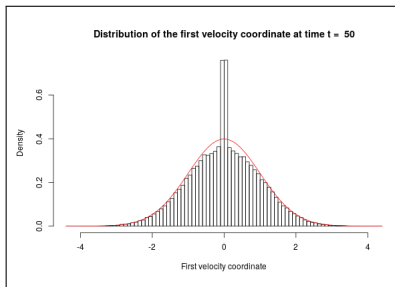
The process built in Chapter 2 provides a natural way to study numerically the convergence through a system of particles. We will focus on the following star-shaped domain (2D).





Qualitative behavior

Initial distribution hereafter: uniform distribution in space, law $\mathcal{N}(0, 0.01 I_2)$ for the velocity
 Parameters: 10^6 particles, $\alpha \equiv 1$ (pure diffuse reflection), M the Maxwellian wall.





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We will rather use the following property: if μ, ν are two measures on a measurable space (E, \mathcal{E}) ,

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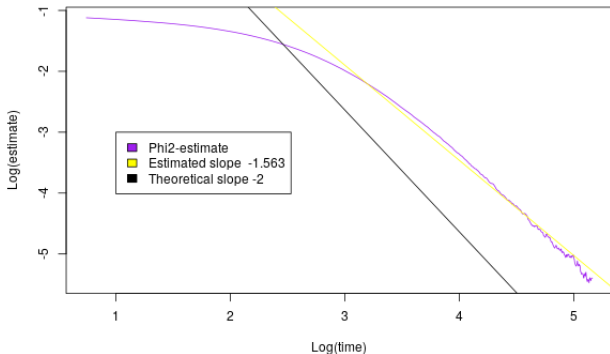
$$\|\mu - \nu\|_{TV} = \frac{1}{2} \sup_{\phi: E \rightarrow [-1,1]} \left| \int \phi d\mu - \int \phi d\nu \right|.$$

Hence we can approximate the total variation by testing the distribution against a function ϕ . In what follows we present estimates corresponding to the choice $\phi_2(x, \nu) = \sqrt{|x|} + \sqrt{|\nu|}$.



Case of the wall Maxwellian

Log-log curve, Estimates in the star-shaped domain with $\alpha = 1$



This is a log-log curve \rightarrow we have a polynomial rate, as expected.
 However, its value is far from the theoretical prediction.



Changing the distribution at the boundary

Instead of using the wall Maxwellian

$$M(v) = \frac{e^{-\frac{|v|^2}{2}}}{2\pi}, \quad v \in \mathbb{R}^2,$$

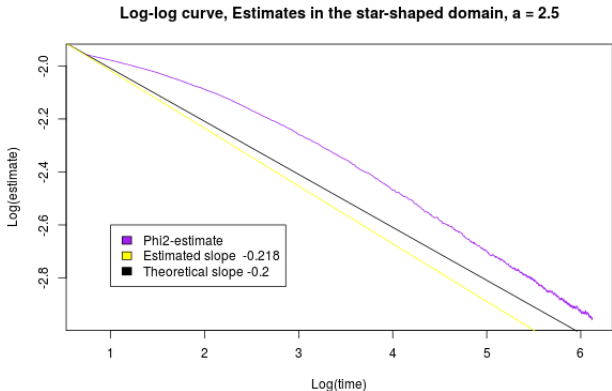
we can modify slightly the distribution to obtain more or less concentration around 0:

$$M_a(v) \propto e^{-\frac{|v|^2}{2}} |v|^{\frac{2}{a}-3}, \quad v \in \mathbb{R}^2, \quad a \in (0, 3).$$

This changes the rate of convergence if the initial data is also adapted. In particular, with the previous initial data, we expect an exponent of the rate equal to $\frac{3}{a} - 1$ for $a \in]1, 3[$ (the problem is slightly more complicated for $a < 1$).



An example: the case $a = 2.5$.



We clearly see the difference with respect to the case $a = 1$! Once again, the empirical rate differs slightly from the theoretical one.



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Two sub-geometric Harris' theorems

Back to the free-transport equation [Chapter 4]

Linking coupling and Lyapunov criteria [Chapter 5]

Linearized equations from collisional kinetic theory

Outlook



Same problem, different strategy: Harris' sub-geometric theorem

Another way to study the convergence of the free-transport equation is to apply Harris' theorem, more precisely the deterministic sub-geometric version of Cañizo and Mischler (following the probabilistic results of Douc-Fort-Guillin and Hairer-Mattingly).



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In what follows, M is the wall Maxwellian, but the temperature is allowed to vary at the boundary. We assume again, for all $x \in \partial\Omega$, $\alpha(x) \geq \alpha_0$ for some $\alpha_0 > 0$.



Sub-geometric Harris' theorem from the probabilistic side

Let $(X_t)_{t \geq 0}$ be a Borel right process with values in (E, \mathcal{E}) , with associated Markov semigroup $(\mathcal{P}_t)_{t \geq 0}$, generator \mathcal{L} , non-explosive, irreducible, aperiodic. Then if



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1. $\exists C \in \mathcal{E}$ compact and petite, i.e. there $\exists a \in \mathcal{P}(\mathbb{R}_+)$ and a σ -finite measure $\nu \neq 0$ on \mathcal{E} such that

$$\forall x \in C, \int_0^\infty \mathcal{P}_t(x, \cdot) a(dt) \geq \nu(\cdot);$$



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2. $\mathcal{L}V \leq -\phi(V) + K1_C$, for some $K \geq 0$, for $\phi \uparrow \infty$, strictly concave (+ technical requirements)

letting $H_\phi(u) = \int_1^u \frac{du}{\phi(u)}$, $\exists \pi$ invariant measure for $(\mathcal{P}_t)_{t \geq 0}$ on E and $C > 0$ s.t. for all $x \in E$,

$$\lim_{t \rightarrow \infty} \phi(H_\phi^{-1}(t)) \|\mathcal{P}_t(x, \cdot) - \pi(\cdot)\|_{TV} = 0.$$



A deterministic result

Deterministic sub-geometric Harris Theorem (Cañizo-Mischler)

With the same notations, if, $1 \leq m_0 \lesssim m_1 \lesssim m_2 \lesssim m_3$ are four weights with

$$\mathcal{L}^* m_1 \leq -m_0 + K_0, \quad \mathcal{L}^* m_3 \leq -m_2 + K_2, \quad K_0, K_2 > 0,$$

and if, for any $R > R_0 > 0$, there exist $T \geq T_0$ and a measure $\nu \neq 0$ such that

$$e^{\mathcal{L}^* T} f \geq \nu \int_{\{|x| \leq R\}} f \, dx, \quad \forall f \in L^1(E)_+ = \{f \in L^1(E), f \geq 0\},$$

then a quantitative rate of convergence, based on an interpolation condition holding between the weights $(m_i)_{i \geq 1}$ can be obtained.



Application to the free-transport problem

E.g., if we let $\langle x \rangle := (1 + |x|^2)^{\frac{1}{2}}$ and if $0 < \delta \leq k$ with $m_0 \simeq 1$, $m_1 \simeq \langle x \rangle^\delta$, $m_2 \simeq \langle x \rangle^{k-\delta}$ and $m_3 \simeq \langle x \rangle^k$ we can show that the final rate is $t^{-\frac{k}{\delta}}$.



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For the free-transport equation, the key quantity to look at is

$$\sigma(x, v) = \inf\{t > 0, x + tv \in \partial\Omega\},$$

which is the time it takes, for a particle starting at 0 in position x with velocity v , to hit the boundary.



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An important fact is that $v \cdot \nabla_x \sigma(x, v) = -1$. This will be the main ingredient of the Lyapunov inequalities. Let $\langle x, v \rangle = (1 + \sigma(x, v))$ on \bar{G} in what follows.



Application to the free-transport problem II

Idea: let $m_3(x, v) = \langle x, v \rangle^k$ in \bar{G} , $m_2(x, v) = k \langle x, v \rangle^{k-1}$. Let $\|\cdot\|_m$ be the weighted L^1 norm with weight $m \geq 1$. Then, for $T > 0$, $\int_G f_0 = 0$,

$$\begin{aligned} \frac{d}{dt} \|f_T\|_{m_3} &\leq - \int_G (v \cdot \nabla_x) |f_T| m_3 \, dv dx \\ &= \int_G |f_T| (v \cdot \nabla_x) m_3 \, dv dx - \int_{\Sigma} (v \cdot n_x) |f_T| m_3 \, dv d\zeta(x) \\ &\leq - \|f_T\|_{m_2} + \underbrace{\int_{\partial\Omega} \widetilde{\gamma_+ f} \int_{\{v' \cdot n_x < 0\}} M(v') |v' \cdot n_x| \left(1 + \frac{\text{diam}(\Omega)}{|v'|}\right)^k \, dv' \, d\zeta(x)}_{=C_k} \end{aligned}$$

We see that $\delta = 1$ with the previous notations. Two issues:

1. Controlling the flux part \rightarrow integrated inequalities.
2. The right quantity to look at is not a norm but rather $1 + \sigma(x, v)$ which behaves as $\frac{1}{|v|}$ for small velocities.



Application to the free-transport problem II

Idea: let $m_3(x, v) = \langle x, v \rangle^k$ in \bar{G} , $m_2(x, v) = k \langle x, v \rangle^{k-1}$. Let $\|\cdot\|_m$ be the weighted L^1 norm with weight $m \geq 1$. Then, for $T > 0$, $\int_G f_0 = 0$,

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We see that $\delta = 1$ with the previous notations. Two issues:

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Note that $f_\infty \equiv M \in L^1_{\langle x, v \rangle^{d-}}(G) \setminus L^1_{\langle x, v \rangle^{(d+1)-}}(G)$ so take $k = d -$

\rightarrow again, rate in $t^{-\frac{k}{\delta}} = t^{-(d-)}$.



A theorem in the exponential case (Meyn-Tweedie, ...)

Theorem

With $(X_t)_{t \geq 0}$ as in Slide 30, the following conditions are equivalent:

1. there exist a compact petite set $C \in \mathcal{E}$ and $\delta > 0$, $\kappa > 1$ such that, for $\tau_C(\delta) = \inf\{t > \delta : X_t \in C\}$,

$$\forall x \in E, \mathbb{E}_x[\kappa^{\tau_C(\delta)}] < \infty, \quad \text{and} \quad \sup_{x \in C} \mathbb{E}_x[\kappa^{\tau_C(\delta)}] < \infty;$$

2. there exist a compact petite set $C \in \mathcal{E}$, $b, \beta > 0$ and $V : E \rightarrow [1, \infty]$, finite at some $x_0 \in E$ such that

$$\mathcal{L}V(x) \leq -\beta V(x) + b1_C(x), \quad \forall x \in E.$$

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Each condition implies that there exist $\rho < 1$, $d > 0$ and an invariant measure π on E such that, for all $x \in E$,

$$\|\mathcal{P}_t(x, \cdot) - \pi(\cdot)\|_{TV} \leq dV(x)\rho^t.$$



The sub-geometric version (Douc-Fort-Guillin, ...)

Theorem

With $(X_t)_{t \geq 0}$ as in Slide 30, let $\phi : [1, \infty) \rightarrow (0, \infty)$ increasing, differentiable, concave. Let H_ϕ defined as before. Consider the two conditions

1. $\exists \delta > 0$ and a compact petite set C such that for all $x \in E$, $\mathbb{E}_x[\int_0^{\tau_C(\delta)} H_\phi^{-1}(s) ds] < \infty$, with a uniform bound on C ;
2. there exist a compact petite set C , a constant $b < \infty$ and $V : X \rightarrow [1, \infty)$ unif. bounded on C such that

$$\mathcal{L}V \leq -\phi(V) + b1_C.$$

Both conditions imply that there exists an invariant measure π on E s.t. for all $x \in E$,

$$\lim_{t \rightarrow \infty} \phi(H_\phi^{-1}(t)) \|\mathcal{P}_t(x, \cdot) - \pi(\cdot)\|_{TV} = 0.$$



No equivalence

- As opposed to the geometric case, there is no equivalence between conditions in the sub-geometric setting.
- Such equivalence is unlikely to hold in this form (the Jensen inequality is in the wrong direction).
- Can we change the conditions to obtain some form of equivalence ?



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In the geometric framework, the proof of equivalence uses the following stopping times: for some $r > 0$, a set C and $T \sim \mathcal{E}(1)$,

$$\tilde{\tau}_C^r := \inf \left\{ t > 0, \int_0^t 1_C(X_s) ds \geq \frac{T}{r} \right\}.$$

Some new conditions

Theorem

Consider $(X_t)_{t \geq 0}$ and ϕ, H_ϕ as before. We have equivalence between:

1. there exist a compact petite set C , $r > 0$ s.t., for $T \sim \mathcal{E}(1)$,

$$\mathbb{E}_x[H_\phi^{-1}(\tilde{\tau}_C^r)] < \infty \text{ for all } x \in E,$$

and this quantity is uniformly bounded on C .

2. $\exists C$ compact, petite on E , $\kappa, \eta > 0$ and $\psi : \mathbb{R}_+ \times E \rightarrow [1, \infty)$ continuous, \uparrow in its first argument, such that (roughly)

$$(\partial_t + \mathcal{L})\psi(t, x) \leq \kappa H_\phi^{-1}(t) 1_C(x) - \phi(H_\phi^{-1}(t)).$$

Both conditions are implied by Condition 2 of the DFG's theorem. They imply the existence of an invariant $\pi \in \mathcal{P}(E)$ with

$$\forall x \in E, \lim_{t \rightarrow \infty} \phi(H_\phi^{-1}(t)) \|\mathcal{P}_t(x, \cdot) - \pi(\cdot)\|_{TV} = 0.$$



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Context and previous results

Adapting hypocoercivity methods to the Maxwell boundary condition

Outlook

Context

In Chapter 6, we add a linear collision operator \mathcal{C} . We consider the same boundary condition as before (with the accommodation coefficient $\alpha \in [0, 1]$), where M is the wall Maxwellian.

$$\partial_t f + v \cdot \nabla_x f = \mathcal{C}f, \quad \text{in } (0, \infty) \times G.$$

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With the hypothesis that we will introduce on \mathcal{C} , this models for instance the Boltzmann equation with or without cut-off or the Landau equation, in the linearized (close to equilibrium) regime. E.g., for Boltzmann

$$\mathcal{C}f(v) = \int_{\mathbb{R}^d \times \mathbb{S}^{d-1}} B(|v - v_*|, \omega) (f' M'_* + M' f'_* - f M_* - M f_*) dv_* d\omega,$$

with $v' = \frac{v+v_*}{2} + \frac{|v-v_*|}{2}\omega$, $v'_* = \frac{v+v_*}{2} - \frac{|v-v_*|}{2}\omega$ the post-collisional velocities, B the collision kernel.

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→ We know that the solution $f_t \rightarrow M$ as $t \rightarrow \infty$. What is the corresponding rate ?



Assumptions on \mathcal{C}

Let us introduce $L_v^2(M^{-1}) := \left\{ f : \mathbb{R}^d \rightarrow \mathbb{R} \mid \int_{\mathbb{R}^d} f^2 M^{-1} dv < +\infty \right\}$
 endowed with $(f, g) := \int_{\mathbb{R}^d} f g M^{-1} dv$ and the associated norm $\| \cdot \|$.



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1. We have $\ker(\mathcal{C}) = \text{Span}\{M, v_1 M, \dots, v_d M, |v|^2 M\}$ on $L_v^2(M^{-1})$ (conservation laws) and we write πf for the projection of f on $\ker(\mathcal{C})$ and $f^\perp := f - \pi f$.

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2. The operator \mathcal{C} is self-adjoint, with $(\mathcal{C}f, f) \leq 0$ and $\exists \lambda > 0$ s.t.

$$(-\mathcal{C}f, f) \geq \lambda \|f^\perp\|, \quad \forall f \in \text{Dom}(\mathcal{C}).$$



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Let $\mathcal{L} = -v \cdot \nabla_x + \mathcal{C}$. We want something of the form

$$\langle -\mathcal{L}f, f \rangle \geq \lambda' |f|^2,$$

for some scalar product $\langle \cdot, \cdot \rangle$ and some $\lambda' > 0$.



Many results in the literature

Short-range interactions (Boltzmann with angular cutoff):

- Guo (2010): exponential convergence in weighted L^∞ space with specular reflection and diffuse reflection when Ω is strictly convex and analytic, see also Briant (2017) $\rightarrow L^2 - L^\infty$ techniques (non-constructive).
- Briant-Guo (2016): constructive results in L^2 if $\alpha > 0$ leading to exponential convergence in weighted L^∞ norm.
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Long-range interactions:

- Guo-Hwang-Jang-Ouyang (2020-2020): Landau equation with specular reflection, exponential convergence in L^2 norm.
- Duan-Liu-Sakamoto-Strain (2020): estimates in L^2 for non cut-off Boltzmann and Landau with specular reflection.



Hypo-coercivity for linear equations

- Assume for simplicity that Ω has no rotational symmetries. Let $\mathcal{H} := \{f : G \rightarrow \mathbb{R}, \int_G f^2 M^{-1} dv dx < \infty\}$.



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- L^2 hypo-coercivity method (DMS): 1. the properties of \mathcal{C} gives some partial coercivity estimate for the scalar product $\langle f, g \rangle = \int_G fg M^{-1} dv dx$ on \mathcal{H} , allowing one to control the microscopic part f^\perp .



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- 2. To control the macroscopic part πf , we add new terms to this scalar product, and consider instead

$$\langle\langle f, g \rangle\rangle = \langle f, g \rangle - \epsilon \langle \bar{\pi} f, \nabla \Delta^{-1} \pi g \rangle_{L_x^2(\Omega)} - \epsilon \langle \nabla \Delta^{-1} \pi f, \bar{\pi} g \rangle_{L_x^2(\Omega)},$$

for $\epsilon > 0$ small enough and well-chosen operators $\bar{\pi}$. We want to obtain an equivalent scalar product (i.e. equivalent corresponding norms).



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for $\epsilon > 0$ small enough and well-chosen operators $\bar{\pi}$. We want to obtain an equivalent scalar product (i.e. equivalent corresponding norms).

- One of the main difficulties: the Poisson equations associated with the Δ^{-1} have to be completed with adapted boundary conditions, to control the macroscopic quantities. This is especially difficult for the momentum component.



Results

Our results are **constructive** and treat the Maxwell boundary condition in **full generality**, i.e. $\alpha \in [0, 1]$. Both Boltzmann (with and without cutoff) and Landau are handled.

Theorem (B., Carrapatoso, Mischler, Tristani)

Let $f_0 \in \mathcal{H}$ such that

- in the case $\alpha \equiv 0$: $\int_G f_0 dv dx = \int_G |v|^2 f_0 dv dx = 0$,
- otherwise: $\int_G f_0 dv dx = 0$.

There exist $\kappa, C > 0$ such that for all f solution with initial data f_0 , for all $t \geq 0$,

$$\|f(t)\|_{\mathcal{H}} \leq C e^{-\kappa t} \|f_0\|_{\mathcal{H}}.$$



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Outlook

- What about the Cercignani-Lampis boundary condition for the free-transport equation ? (in progress)
- Following the first point, what happens in collisional kinetic theory with this new boundary condition ?
- The stochastic process defined in Chapter 2 has recently been adapted in order to obtain simple NESS (non-equilibrium steady states). Can coupling methods (or sticky couplings, see EGZ), give results in this case ?
- Interactions of the new equivalent conditions with weak Poincaré/Cheeger's inequalities and sticky coupling. (in progress)
- Going beyond the L^2 case for the Maxwell boundary condition in collisional kinetic theory ?