

Complexity Dichotomies for a Generic Hypergraph Problem

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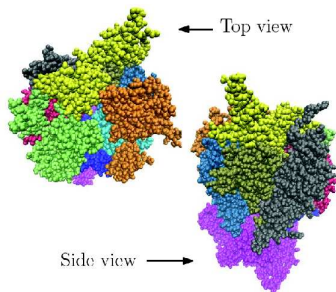
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- 2 Definition of the problem
- 3 Complexity dichotomy
- 4 Parameterized complexity
- 5 Conclusion

Motivations

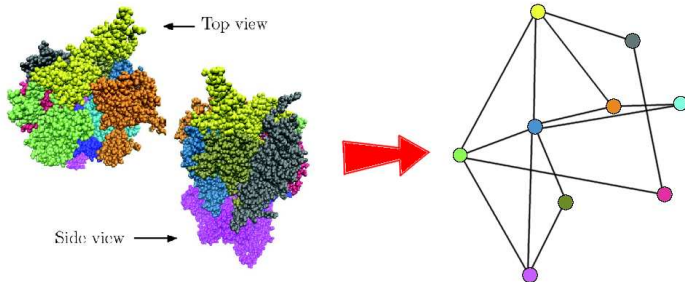
- **Structural biology:** studies the structure of biological macromolecules
 - ▶ which sub-units a given complex is made of?
 - ▶ how are these sub-units organized?



- Experimental (chemical) methods provide either
 - ▶ high resolution (atomic level) of small complexes: X-ray crystallography
 - ▶ low resolution of large complexes: mass spectrometry→ structure of large complexes?

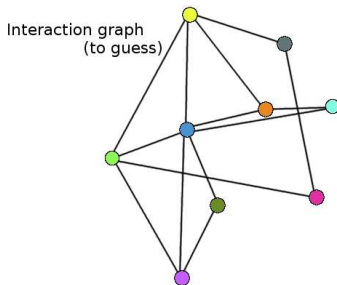
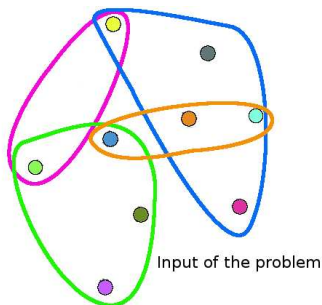
- Goal: find the **interaction graph**:

- ▶ nodes are the sub-units
- ▶ edge between two sub-units if they are adjacent



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- What is the input of the problem?

- ▶ by modifying the chemical conditions, one can **split the complex into smaller pieces**
 - ▶ then, **mass spectrometry** allows us to know:
 - ★ the list of all sub-units of the complex
 - ★ the sub-units involved in each piece
- **they form connected subgraphs in the interaction graph**

⇒ we obtain a hypergraph

Motivations

Minimum Connectivity Overlay Problem

Input: a hypergraph $H = (V, \mathcal{E})$

Output: a graph $G = (V, E)$ such that:

- for every $S \in \mathcal{E}$, $G[S]$ is connected
- $|E(G)|$ is minimum

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Related work

- studied in different contexts
 - ▶ network design
 - ▶ users sharing topics of interest (social network)
 - ▶ ...
- NP-hard, $O(\log(n))$ -approximable, $o(\log(n))$ -inapproximable, FPT, ...

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Minimum \mathcal{C} Connectivity \mathcal{F} Overlay Problem

Input: a hypergraph $H = (V, \mathcal{E})$

Output: a graph $G = (V, E)$ such that:

- for every $S \in \mathcal{E}$, $G[S]$ is **connected** <your favourite graph property here>
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Our objective:

- generalization of the problem to other properties
- for which graph properties the problem is **Polynomial/NP-hard** and **FPT/W[.]**-hard?

Let \mathcal{F} be a graph family

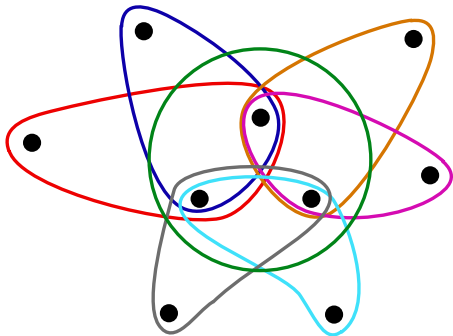
Minimum \mathcal{F} -Overlay

Input: a hypergraph $H = (V, \mathcal{E})$

Output: a graph $G = (V, E)$ such that:

- for every $S \in \mathcal{E}$, $G[S]$ has a **spanning** subgraph in \mathcal{F}
→ we say that G **overlays** \mathcal{F} on H
- $|E(G)|$ is minimum

Example: \mathcal{F} = the set of all stars



Let \mathcal{F} be a graph family

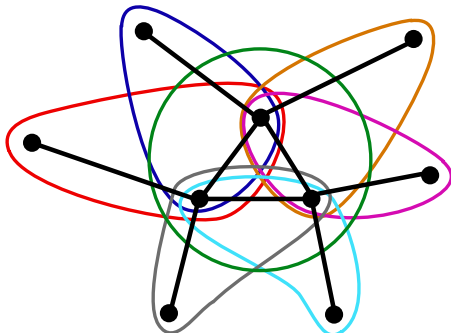
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Some observations:

- if \mathcal{F} is the set of all trees, then we obtain the previous connectivity problem
- G overlays \mathcal{F} on $H \Rightarrow G$ plus any edge overlays \mathcal{F} on H
 \Rightarrow the complete graph on $|V|$ vertices (almost) always overlay \mathcal{F} on H

Our results

- complexity dichotomy: for every \mathcal{F} , we can tell whether Minimum \mathcal{F} -Overlay is Polynomial or NP-complete
- parameterized algorithms: for almost every \mathcal{F} for which the problem is NP-complete, we can tell whether the problem is FPT or W-hard

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Some obvious polynomial cases:

- if \mathcal{F} contains all edgeless graphs, then the edgeless graph is optimal
- if $\mathcal{F} =$ all cliques, then "a clique on every hyperedge" is optimal

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These cases are *more or less* the only polynomial ones

Let $\mathcal{F}_p =$ graphs of \mathcal{F} with p vertices

Theorem (easy part)

If, for every $p > 0$, either $\mathcal{F}_p = \emptyset$ or $\mathcal{F}_p = \{K_p\}$ or $\bar{K}_p \in \mathcal{F}_p$,
then **Minimum \mathcal{F} -Overlay is polynomial**

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Sketch of the proof (by induction on p)

Def.: \mathcal{F}^- = graphs obtained from \mathcal{F}_p by removing a vertex (all possibilities)

- if \mathcal{F}^- satisfies the statement, we reduce from Minimum \mathcal{F}^- -Overlay:

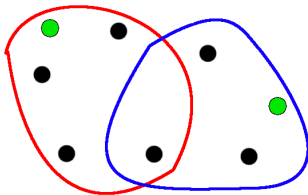
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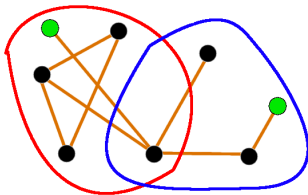
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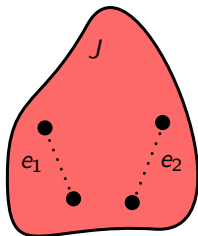
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- what if \mathcal{F}^- is a polynomial case?
 - ▶ if $\mathcal{F}^- = \{K_{p-1}\}$, then $\mathcal{F}_p = \{K_p\}$ (impossible)
 - ▶ if $\bar{K}_{p-1} \in \mathcal{F}^-$, then \mathcal{F}_p contains a subgraph of the star $K_{1,p}$

Lemma

Minimum \mathcal{F}_p -Overlay is NP-hard if there is a graph J of order p and two distinct non-edges e_1, e_2 of J such that:

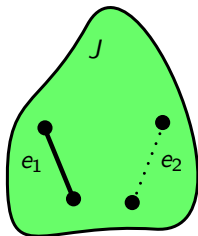
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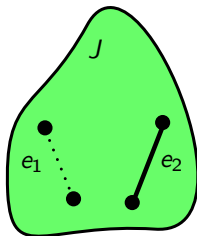
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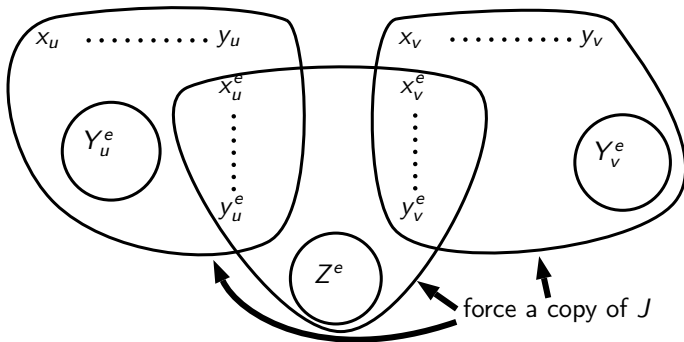


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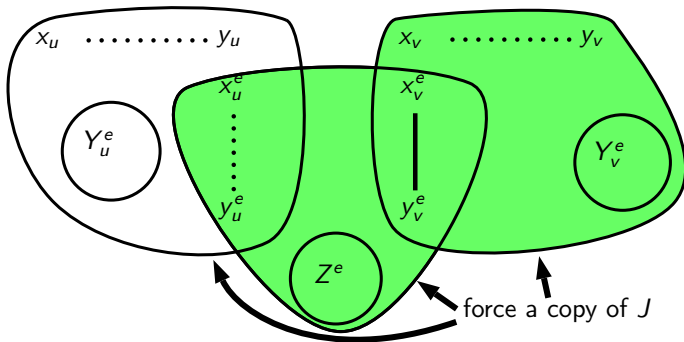


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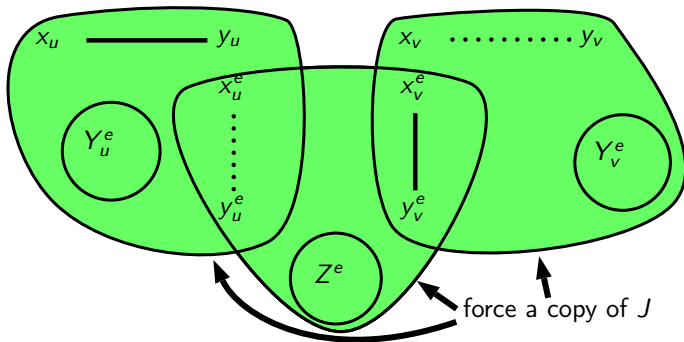


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If \mathcal{F}_p contains a subgraph S of the star $K_{1,p}$:
(assume minimality of S)

- if $S \neq K_{1,p}$: ok



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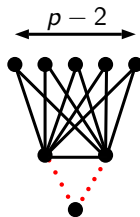
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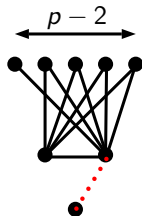
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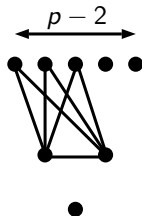
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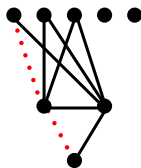
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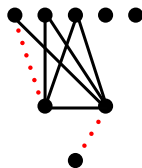
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Parameterized complexity

Minimum \mathcal{F} -Overlay is NP-hard for most non-trivial \mathcal{F}

- for which \mathcal{F} the problem is FPT or W[1]-hard?

Here: $k =$ "natural parameter" = total number of edges in a solution

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If $\mathcal{F} =$ the set of all trees. Bounded search tree:

- if there is a hyperedge with $\geq k + 2$ vertices, answer **"No"**
- otherwise: branch on every possible connected graph for every hyperedge
 $\Rightarrow O^*(2^{k \log(k)})$ algorithm

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Same approach gives:

Theorem

If there is a non-decreasing function $f : \mathbb{N} \rightarrow \mathbb{N}$ with $\lim_{n \rightarrow \infty} f(n) = \infty$ such that for all $F \in \mathcal{F}$ we have $|E(F)| \geq f(|V(F)|)$ then **Minimum \mathcal{F} -Overlay is FPT**

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Examples of \mathcal{F} satisfying the statement:

- whenever \mathcal{F} is finite
- $\mathcal{F} =$ all stars
- $\mathcal{F} =$ hamiltonian graphs
- $\mathcal{F} =$ graphs of minimum degree d
- $\mathcal{F} = c$ -connected graphs
- ...

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Examples of \mathcal{F} **not satisfying the statement**:

- graphs having an arbitrary number of isolated vertices
 - ▶ graphs of maximum degree D
 - ▶ graphs containing a matching of size at least c
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\mathcal{F} loose family \Leftrightarrow for all $F \in \mathcal{F}$, $F + \text{isolated vertices} \in \mathcal{F}$
 \Rightarrow removes the "spanning" constraint on every hyperedge

Parameterized complexity

Theorem

If there is a non-decreasing function $f : \mathbb{N} \rightarrow \mathbb{N}$ with $\lim_{n \rightarrow \infty} f(n) = \infty$ such that for all $F \in \mathcal{F}$ we have $|E(F)| \geq f(|V(F)|)$ then **Minimum \mathcal{F} -Overlay is FPT**

Examples of \mathcal{F} **not satisfying the statement**:

- graphs having an arbitrary number of isolated vertices
 - ▶ graphs of maximum degree D
 - ▶ graphs containing a matching of size at least c
 - ▶ ...

\mathcal{F} loose family \Leftrightarrow for all $F \in \mathcal{F}$, $F + \text{isolated vertices} \in \mathcal{F}$
 \Rightarrow removes the "spanning" constraint on every hyperedge

Theorem

Let \mathcal{F} be a loose family of graphs.

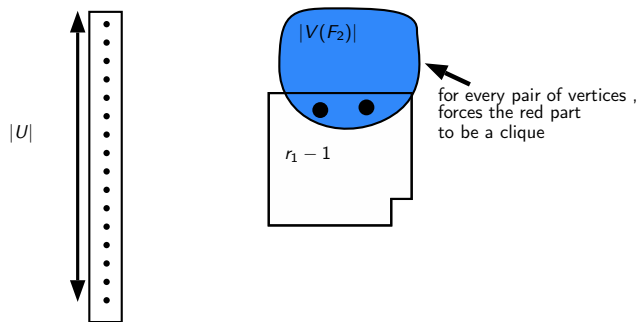
If $\bar{K}_p \in \mathcal{F}$ for some p , then **Minimum \mathcal{F} -Overlay is FPT**, otherwise, **it is W[1]-hard**

W[1]-hardness

Let U, \mathcal{S}, k be a **Hitting Set** instance (U =Universe, \mathcal{S} =subsets of U , $k \in \mathbb{N}$)

F_1 = graph of \mathcal{F} with min. number of non-isolated vertices r_1

F_2 = graph of \mathcal{F} with min. number of edges

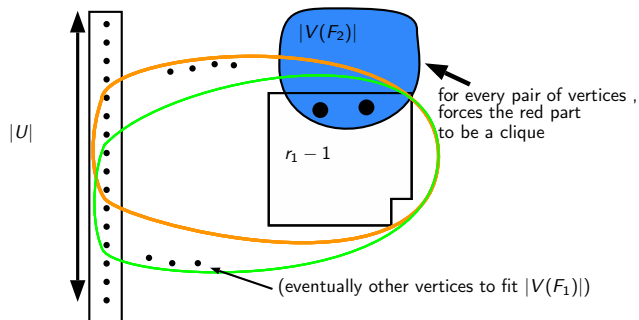


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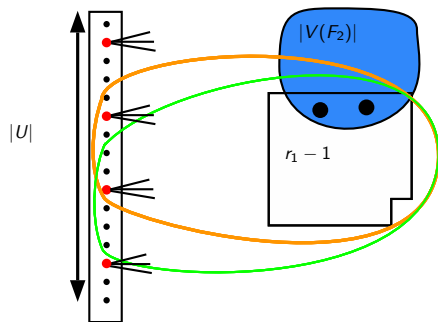


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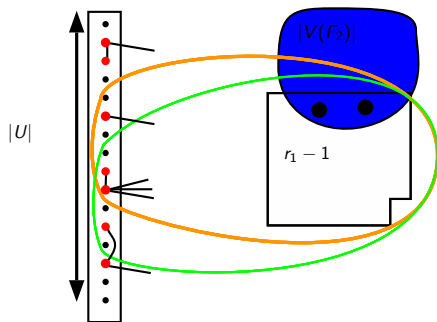
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$$k' = \binom{|V(F_2)|-1}{2} |E(F_2)| + k\delta(F_1)$$

- Conversely: right part must be a clique \Rightarrow left part covers $\leq k\delta(F_1)$ edges.
- The non-isolated vertices of the left part is a hitting set

But: no guarantee that it is an independent set (e.g.: F_1 disconnected)

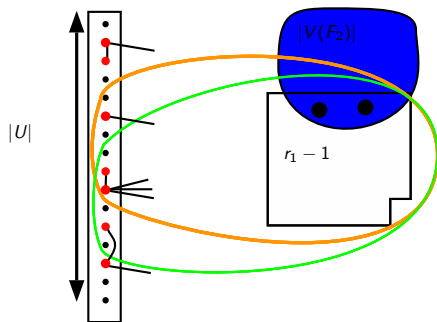
\Rightarrow What is the maximum number of (non-isolated) vertices that can cover $k\delta(F_1)$ edges?

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Let U, \mathcal{S}, k be a **Hitting Set** instance (U =Universe, \mathcal{S} =subsets of U , $k \in \mathbb{N}$)

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Theorem [Chen, Lin, FOCS 2016]

Approximating Hitting Set to any constant is W[1]-hard

⇒ reduce from $\text{Gap}_{2\delta}(F_1)$ Hitting Set

- Conversely: right part must be a clique ⇒ left part covers $\leq k\delta(F_1)$ edges.
- The non-isolated vertices of the left part is a hitting set
But: no guarantee that it is an independent set (e.g.: F_1 disconnected)
⇒ What is the maximum number of (non-isolated) vertices that can cover $k\delta(F_1)$ edges? $2k\delta(F_1)$ (matching)

Open problems, further research

Parameterized algorithms

- what about \mathcal{F} which are not loose, but does not fall into the FPT case?
 - ▶ "almost loose": for all $F \in \mathcal{F}$, $F + \bar{K}_{g(i)} \in \mathcal{F} \forall i$
 - ▶ W[1]-hard if $g = \text{polynomial}$
 - ▶ what if $g(i) = 2^i$?

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Variants of the problem

- require that for every hyperedge $S \in \mathcal{E}$, $G[S]$ is **isomorphic** to some $F \in \mathcal{F}$
 \Rightarrow forbids additional edges

now, testing satisfiability is no longer polynomial

NP-hard even if $\mathcal{F} = \{P_3\}$

complexity dichotomy?

- add some constraints on the output graph:
 - ▶ $\Delta(G) \leq d$
 - ▶ bounded treewidth?
 - ▶ already some work with "planarity" constraint (hypergraph drawing)

Voilà !
Questions ?